

Stability Conditions and Applications

Cristian Martinez
Universidad del Norte
Barranquilla, Colombia

June 4th, 2020

What does Moduli Theory study?

What does Moduli Theory study?

- Classification problems.

What does Moduli Theory study?

- Classification problems.
- Want a space (algebraic variety, scheme, algebraic space, stack) that parametrizes equivalence classes of objects.

What does Moduli Theory study?

- Classification problems.
- Want a space (algebraic variety, scheme, algebraic space, stack) that parametrizes equivalence classes of objects.
- Want to be able to deform objects (taking limits): a compact moduli space.

An algebraic example

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod } \mathbb{Z}$).

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions.

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions. The order n is a discrete invariant of the isomorphism classes.

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions. The order n is a discrete invariant of the isomorphism classes. The level of difficulty of solving this problem varies with our choice of n .

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions. The order n is a discrete invariant of the isomorphism classes. The level of difficulty of solving this problem varies with our choice of n .
- If $G \in \text{mod}_{\mathbb{Z}}$ is finitely generated, then $G \cong \mathbb{Z}^{\oplus r} \oplus G'$ where G' is finite.

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions. The order n is a discrete invariant of the isomorphism classes. The level of difficulty of solving this problem varies with our choice of n .
- If $G \in \text{mod}_{\mathbb{Z}}$ is finitely generated, then $G \cong \mathbb{Z}^{\oplus r} \oplus G'$ where G' is finite. In this case the isomorphism class of G has two discrete invariants:

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions. The order n is a discrete invariant of the isomorphism classes. The level of difficulty of solving this problem varies with our choice of n .
- If $G \in \text{mod}_{\mathbb{Z}}$ is finitely generated, then $G \cong \mathbb{Z}^{\oplus r} \oplus G'$ where G' is finite. In this case the isomorphism class of G has two discrete invariants:

$$r = \text{rank of } G, \quad \text{and} \quad |G'| = \text{order of torsion of } G.$$

An algebraic example

Let \mathcal{A} be an abelian category (for instance, $\text{mod}_{\mathbb{Z}}$). Want to classify isomorphism classes of objects in \mathcal{A} :

- If $G \in \text{mod}_{\mathbb{Z}}$ and $|G| = n$, then the classification problem has finitely many solutions. The order n is a discrete invariant of the isomorphism classes. The level of difficulty of solving this problem varies with our choice of n .
- If $G \in \text{mod}_{\mathbb{Z}}$ is finitely generated, then $G \cong \mathbb{Z}^{\oplus r} \oplus G'$ where G' is finite. In this case the isomorphism class of G has two discrete invariants:

$$r = \text{rank of } G, \quad \text{and} \quad |G'| = \text{order of torsion of } G.$$

Once again, if we fix the discrete invariants then the classification problem has finitely many solutions.

Some geometric examples

Some geometric examples

- The projective space $\mathbb{C}P^n$ parametrizes 1-dimensional vector subspaces of \mathbb{C}^{n+1} .

Some geometric examples

- The projective space $\mathbb{C}\mathbb{P}^n$ parametrizes 1-dimensional vector subspaces of \mathbb{C}^{n+1} . This parameter space admits a construction as a quotient

Some geometric examples

- The projective space $\mathbb{C}\mathbb{P}^n$ parametrizes 1-dimensional vector subspaces of \mathbb{C}^{n+1} . This parameter space admits a construction as a quotient

$$\mathbb{C}\mathbb{P}^n = (\mathbb{C}^{n+1} \setminus \{0\})/\mathbb{C}^*.$$

Some geometric examples

- The projective space $\mathbb{C}\mathbb{P}^n$ parametrizes 1-dimensional vector subspaces of \mathbb{C}^{n+1} . This parameter space admits a construction as a quotient

$$\mathbb{C}\mathbb{P}^n = (\mathbb{C}^{n+1} \setminus \{0\})/\mathbb{C}^*.$$

The Zariski topology on $\mathbb{C}\mathbb{P}^n$ is the topology whose closed subsets are the zero sets of complex homogeneous polynomials in $n + 1$ variables.

Some geometric examples

- The projective space $\mathbb{C}\mathbb{P}^n$ parametrizes 1-dimensional vector subspaces of \mathbb{C}^{n+1} . This parameter space admits a construction as a quotient

$$\mathbb{C}\mathbb{P}^n = (\mathbb{C}^{n+1} \setminus \{0\})/\mathbb{C}^*.$$

The Zariski topology on $\mathbb{C}\mathbb{P}^n$ is the topology whose closed subsets are the zero sets of complex homogeneous polynomials in $n + 1$ variables. Each of those closed subsets is called a **projective variety**.

Some geometric examples

- A **conic** is the zero set of a complex homogeneous polynomial of degree 2 in three variables:

Some geometric examples

- A **conic** is the zero set of a complex homogeneous polynomial of degree 2 in three variables:

$$a_0X_0^2 + a_1X_1^2 + a_2X_2^2 + a_3X_0X_1 + a_4X_0X_2 + a_5X_1X_2 = 0$$

Some geometric examples

- A **conic** is the zero set of a complex homogeneous polynomial of degree 2 in three variables:

$$a_0X_0^2 + a_1X_1^2 + a_2X_2^2 + a_3X_0X_1 + a_4X_0X_2 + a_5X_1X_2 = 0$$

The coefficients of the polynomial determine the conic, and scaling the coefficients at the same time does not change the conic.

Some geometric examples

- A **conic** is the zero set of a complex homogeneous polynomial of degree 2 in three variables:

$$a_0X_0^2 + a_1X_1^2 + a_2X_2^2 + a_3X_0X_1 + a_4X_0X_2 + a_5X_1X_2 = 0$$

The coefficients of the polynomial determine the conic, and scaling the coefficients at the same time does not change the conic. Then a parameter space for all conics is

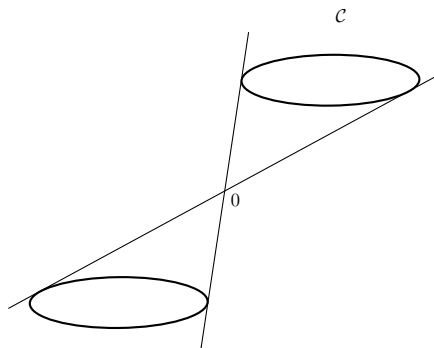
$$\mathbb{C}P^5 = \{[a_0, a_1, a_3, a_4, a_5]\}$$

Some geometric examples

Each conic $C \subset \mathbb{C}\mathbb{P}^2$ can be seen as a family of lines in \mathbb{C}^3 passing through the origin, i.e., a family of 1-dimensional vector subspaces of \mathbb{C}^3 :

Some geometric examples

Each conic $C \subset \mathbb{C}P^2$ can be seen as a family of lines in \mathbb{C}^3 passing through the origin, i.e., a family of 1-dimensional vector subspaces of \mathbb{C}^3 :

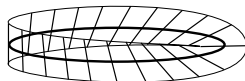
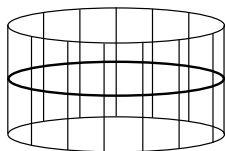


Some geometric examples

There are nicer families of vector spaces that can be parametrized by projective varieties, these are called **vector bundles**.

Some geometric examples

There are nicer families of vector spaces that can be parametrized by projective varieties, these are called **vector bundles**.



Our geometric objects

Our geometric objects

- Vector bundles.

Our geometric objects

- Vector bundles.
- Resulting moduli space is “too big”

How to get a reasonable moduli space of vector bundles?

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .
- Choose X to be as nice as you can:

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .
- Choose X to be as nice as you can: smooth complex projective variety of dimension n .

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .
- Choose X to be as nice as you can: smooth complex projective variety of dimension n .
- To control the size of the moduli space, fix also some discrete invariants:

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .
- Choose X to be as nice as you can: smooth complex projective variety of dimension n .
- To control the size of the moduli space, fix also some discrete invariants: Chern classes $ch = (ch_0, ch_1, \dots, ch_n)$.

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .
- Choose X to be as nice as you can: smooth complex projective variety of dimension n .
- To control the size of the moduli space, fix also some discrete invariants: Chern classes $ch = (ch_0, ch_1, \dots, ch_n)$.
- To get a proper moduli space allow at least coherent sheaves, i.e., work in the category $Coh(X)$.

How to get a reasonable moduli space of vector bundles?

- Fix the base, i.e., vector bundles over a fixed variety X .
- Choose X to be as nice as you can: smooth complex projective variety of dimension n .
- To control the size of the moduli space, fix also some discrete invariants: Chern classes $ch = (ch_0, ch_1, \dots, ch_n)$.
- To get a proper moduli space allow at least coherent sheaves, i.e., work in the category $Coh(X)$.
- Still not good enough! We need to add an extra condition: a “stability condition”

Mumford slope

Mumford slope

- For an ample class $\omega \in N^1(X)_{\mathbb{Q}}$

Mumford slope

- For an ample class $\omega \in N^1(X)_{\mathbb{Q}}$, the Mumford slope of $E \in \text{Coh}(X)$ with respect to ω is

Mumford slope

- For an ample class $\omega \in N^1(X)_{\mathbb{Q}}$, the Mumford slope of $E \in \text{Coh}(X)$ with respect to ω is

$$\mu_{\omega}(E) := \frac{ch_1(E) \cdot \omega^{n-1}}{ch_0(E)\omega^n}$$

Mumford slope

- For an ample class $\omega \in N^1(X)_{\mathbb{Q}}$, the Mumford slope of $E \in \text{Coh}(X)$ with respect to ω is

$$\mu_{\omega}(E) := \frac{ch_1(E) \cdot \omega^{n-1}}{ch_0(E)\omega^n} = \frac{\det(E) \cdot \omega^{n-1}}{\text{rk}(E)\omega^n}.$$

Mumford slope

- For an ample class $\omega \in N^1(X)_{\mathbb{Q}}$, the Mumford slope of $E \in \text{Coh}(X)$ with respect to ω is

$$\mu_{\omega}(E) := \frac{ch_1(E) \cdot \omega^{n-1}}{ch_0(E)\omega^n} = \frac{\det(E) \cdot \omega^{n-1}}{\text{rk}(E)\omega^n}.$$

Note: μ_{ω} can be defined for all coherent sheaves by declaring $\mu_{\omega}(E) = +\infty$ if $ch_0(E) = 0$.

Classical semistabilities

Definition

Let $E \in \text{Coh}(X)$ be a torsion-free sheaf. We say that E is **Mumford semistable** if for all subsheaves $A \hookrightarrow E$ we have

$$\mu_{\omega}(A) \leq \mu_{\omega}(E);$$

Classical semistabilities

Definition

Let $E \in \text{Coh}(X)$ be a torsion-free sheaf. We say that E is **Mumford semistable** if for all subsheaves $A \hookrightarrow E$ we have

$$\mu_\omega(A) \leq \mu_\omega(E);$$

it is called **Gieseker semistable** if moreover

$$p_\omega(A)(t) \leq p_\omega(E)(t),$$

where $p_\omega(\cdot)(t)$ is the reduced Hilbert polynomial with respect to ω .

Classical semistabilities

Definition

Let $E \in \text{Coh}(X)$ be a torsion-free sheaf. We say that E is **Mumford semistable** if for all subsheaves $A \hookrightarrow E$ we have

$$\mu_\omega(A) \leq \mu_\omega(E);$$

it is called **Gieseker semistable** if moreover

$$p_\omega(A)(t) \leq p_\omega(E)(t),$$

where $p_\omega(\cdot)(t)$ is the reduced Hilbert polynomial with respect to ω . In the case that $n = 2$ the Gieseker condition becomes

$$\left(\frac{\chi(A)}{ch_0(A)\omega^2} - \frac{\chi(E)}{ch_0(E)\omega^2} \right) \omega^2 + t(\mu_\omega(A) - \mu_\omega(E)) \leq 0 \quad \text{for } t \gg 0.$$

Classical semistabilities

Definition

Let $E \in \text{Coh}(X)$ be a torsion-free sheaf. We say that E is **Mumford semistable** if for all subsheaves $A \hookrightarrow E$ we have

$$\mu_\omega(A) \leq \mu_\omega(E);$$

it is called **Gieseker semistable** if moreover

$$p_\omega(A)(t) \leq p_\omega(E)(t),$$

where $p_\omega(\cdot)(t)$ is the reduced Hilbert polynomial with respect to ω . In the case that $n = 2$ the Gieseker condition becomes

$$\left(\frac{\chi(A)}{ch_0(A)\omega^2} - \frac{\chi(E)}{ch_0(E)\omega^2} \right) \omega^2 + t(\mu_\omega(A) - \mu_\omega(E)) \leq 0 \quad \text{for } t \gg 0.$$

Note: These semistabilities depend on the ample class ω .

Two important properties

Two important properties

- (Harder-Narasimhan) Every nonzero $E \in \text{Coh}(X)$ has a unique filtration

$$0 \subset E_0 \subset E_1 \subset \cdots \subset E_n = E$$

such that E_0 is the torsion subsheaf of E , and the factors $F_i = E_i/E_{i-1}$ are Mumford semistable of decreasing slopes.

Two important properties

- (Harder-Narasimhan) Every nonzero $E \in \text{Coh}(X)$ has a unique filtration

$$0 \subset E_0 \subset E_1 \subset \cdots \subset E_n = E$$

such that E_0 is the torsion subsheaf of E , and the factors $F_i = E_i/E_{i-1}$ are Mumford semistable of decreasing slopes.

- For fixed Chern character v , there is a projective coarse moduli space $M_\omega(v)$ parametrizing S -equivalence classes of Gieseker semistable sheaves of type v .

Primary goal

Study the geometry of $M_\omega(v)$:

Primary goal

Study the geometry of $M_\omega(v)$:

- Is this space irreducible or smooth? Can we understand its singular locus? What is its dimension?

Primary goal

Study the geometry of $M_\omega(v)$:

- Is this space irreducible or smooth? Can we understand its singular locus? What is its dimension?
- How can we produce varieties that are birational to $M_\omega(v)$?

Some answers on surfaces

Some answers on surfaces

Suppose for the moment that $n = 2$ and let

$$\Delta(v) = ch_1^2 - 2ch_0ch_2.$$

Some answers on surfaces

Suppose for the moment that $n = 2$ and let

$$\Delta(v) = ch_1^2 - 2ch_0ch_2.$$

- (Bogomolov inequality): If E is Mumford semistable then $\Delta(E) \geq 0$.

Some answers on surfaces

Suppose for the moment that $n = 2$ and let

$$\Delta(v) = ch_1^2 - 2ch_0ch_2.$$

- (Bogomolov inequality): If E is Mumford semistable then $\Delta(E) \geq 0$.
- If $\Delta(v) \gg 0$ then $M_\omega(v)$ is normal and irreducible of dimension $\Delta(v) - (ch_0^2 - 1)\chi(\mathcal{O}_X)$.

Some answers on surfaces

Suppose for the moment that $n = 2$ and let

$$\Delta(v) = ch_1^2 - 2ch_0ch_2.$$

- (Bogomolov inequality): If E is Mumford semistable then $\Delta(E) \geq 0$.
- If $\Delta(v) \gg 0$ then $M_\omega(v)$ is normal and irreducible of dimension $\Delta(v) - (ch_0^2 - 1)\chi(\mathcal{O}_X)$.
- If $\Delta(v) \gg 0$ and ω, ω' are ample then the moduli spaces $M_\omega(v)$ and $M_{\omega'}(v)$ are birational.

Some answers on surfaces

Suppose for the moment that $n = 2$ and let

$$\Delta(v) = ch_1^2 - 2ch_0ch_2.$$

- (Bogomolov inequality): If E is Mumford semistable then $\Delta(E) \geq 0$.
- If $\Delta(v) \gg 0$ then $M_\omega(v)$ is normal and irreducible of dimension $\Delta(v) - (ch_0^2 - 1)\chi(\mathcal{O}_X)$.
- If $\Delta(v) \gg 0$ and ω, ω' are ample then the moduli spaces $M_\omega(v)$ and $M_{\omega'}(v)$ are birational.

Note: For most surfaces $N^1(X) \cong \mathbb{Z}$ and so $M_\omega(v)$ and $M_{\omega'}(v)$ are actually isomorphic.

Some answers on surfaces

Suppose for the moment that $n = 2$ and let

$$\Delta(v) = ch_1^2 - 2ch_0ch_2.$$

- (Bogomolov inequality): If E is Mumford semistable then $\Delta(E) \geq 0$.
- If $\Delta(v) \gg 0$ then $M_\omega(v)$ is normal and irreducible of dimension $\Delta(v) - (ch_0^2 - 1)\chi(\mathcal{O}_X)$.
- If $\Delta(v) \gg 0$ and ω, ω' are ample then the moduli spaces $M_\omega(v)$ and $M_{\omega'}(v)$ are birational.

Note: For most surfaces $N^1(X) \cong \mathbb{Z}$ and so $M_\omega(v)$ and $M_{\omega'}(v)$ are actually isomorphic. Is there a way to produce interesting birational models in this case?

Bridgeland's idea

Bridgeland's idea

Stability is not only a numerical condition: $Coh(X)$ is part of the stability data:

Bridgeland's idea

Stability is not only a numerical condition: $\text{Coh}(X)$ is part of the stability data:

Classical	Bridgeland
$\text{Coh}(X)$	Abelian subcategory $\mathcal{A} \subset D^b(X)$
$Z_M = -ch_1\omega^{n-1} + ich_0\omega^n$	$Z: K(\mathcal{A}) \rightarrow \mathbb{C}$
$ch_0(\mathcal{E}) = 0$ implies $ch_1(\mathcal{E})\omega^{n-1} \geq 0$	$\Im m(Z(E)) = 0$ implies $\Re e(Z(E)) > 0$
μ_M	$\mu_Z = \frac{-\Re e(Z)}{\Im m(Z)}$
HN filtrations	Impose this condition
$\Delta(E) \geq 0$ for semistables	Support property

The stability manifold

The stability manifold

- A stability condition is a pair $\sigma = (Z, \mathcal{A})$ satisfying the conditions of the table above.

The stability manifold

- A stability condition is a pair $\sigma = (Z, \mathcal{A})$ satisfying the conditions of the table above.
- We say that $\sigma = (Z, \mathcal{A})$ is **numerical** if Z factors through the Chern character map. We say that σ is **geometric** if it is numerical and all skyscraper sheaves \mathbb{C}_x are σ -stable.

The stability manifold

- A stability condition is a pair $\sigma = (Z, \mathcal{A})$ satisfying the conditions of the table above.
- We say that $\sigma = (Z, \mathcal{A})$ is **numerical** if Z factors through the Chern character map. We say that σ is **geometric** if it is numerical and all skyscraper sheaves \mathbb{C}_x are σ -stable.

Theorem (Bridgeland, 2002)

There is a complex manifold $\text{Stab}(X)$ parametrizing numerical stability conditions on X . Moreover, for a fixed Chern character v , $\text{Stab}(X)$ admits a locally finite wall and chamber decomposition such that σ and σ' are in the same chamber if and only if the sets of σ -semistable and σ' -semistable objects of type v are the same.

Why do we care about geometric stability conditions?

Why do we care about geometric stability conditions?

- (Bridgeland; Macrì) If X is a curve then Bridgeland stability is essentially Mumford stability:

Why do we care about geometric stability conditions?

- (Bridgeland; Macrì) If X is a curve then Bridgeland stability is essentially Mumford stability:

$$\mathcal{A} = \text{Coh}(C)$$

Why do we care about geometric stability conditions?

- (Bridgeland; Macrì) If X is a curve then Bridgeland stability is essentially Mumford stability:

$$\mathcal{A} = \text{Coh}(C), \quad Z(E) = -\text{deg}(E) + \sqrt{-1}\text{rk}(E)$$

Why do we care about geometric stability conditions?

- (Bridgeland; Macrì) If X is a curve then Bridgeland stability is essentially Mumford stability:

$$\mathcal{A} = \text{Coh}(C), \quad Z(E) = -\text{deg}(E) + \sqrt{-1}\text{rk}(E) \implies \mu_Z(E) = \frac{\text{deg}(E)}{\text{rk}(E)}$$

Why do we care about geometric stability conditions?

- (Bridgeland; Macrì) If X is a curve then Bridgeland stability is essentially Mumford stability:

$$\mathcal{A} = \text{Coh}(C), \quad Z(E) = -\deg(E) + \sqrt{-1}\text{rk}(E) \implies \mu_Z(E) = \frac{\deg(E)}{\text{rk}(E)}$$

- (Bridgeland) If X is a surface then for every Chern character v there is a distinguished chamber in the wall and chamber decomposition of $\text{Stab}(X)$ such that

$$E \text{ is } \sigma\text{-semistable} \iff E \text{ is } \omega\text{-Gieseker semistable}$$

Why do we care about geometric stability conditions?

Why do we care about geometric stability conditions?

- (Bertram) If X is a surface then for every fixed Chern character v there is a family of geometric stability conditions $\sigma_t = (Z_t, \mathcal{A}_t)$ with

$$\frac{\Re(Z_t(A))}{ch_0(A)} = - \left(\frac{\chi(A)}{ch_0(A)\omega^2} - \frac{\chi(v)}{ch_0(v)\omega^2} \right) \omega^2 - t(\mu_\omega(A) - \mu_\omega(v)).$$

Why do we care about geometric stability conditions?

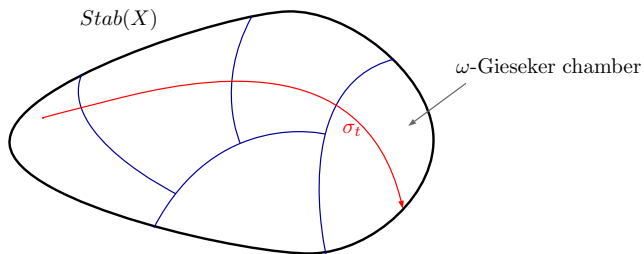
- (Bertram) If X is a surface then for every fixed Chern character v there is a family of geometric stability conditions $\sigma_t = (Z_t, \mathcal{A}_t)$ with

$$\frac{\Re(Z_t(A))}{ch_0(A)} = - \left(\frac{\chi(A)}{ch_0(A)\omega^2} - \frac{\chi(v)}{ch_0(v)\omega^2} \right) \omega^2 - t(\mu_\omega(A) - \mu_\omega(v)).$$

- (Bertram, M.) Moreover, the path $\{\sigma_t\}_{t>0} \subset \text{Stab}(X)$ enters the ω -Gieseker chamber for $t \gg 0$ and never leaves.

Why do we care about geometric stability conditions?

Why do we care about geometric stability conditions?



Why do we care about geometric stability conditions?

Why do we care about geometric stability conditions?

Theorem (Bertram, M., Wang)

If $X = \mathbb{P}^2$ then as we decrease the parameter t the moduli spaces $M_{\sigma_t}(v)$ are precisely all the birational models appearing in the MMP for $M_{\omega}(v)$.

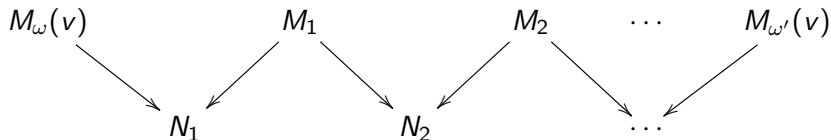
Why do we care about geometric stability conditions?

Theorem (Bertram, M., Wang)

If $X = \mathbb{P}^2$ then as we decrease the parameter t the moduli spaces $M_{\sigma_t}(v)$ are precisely all the birational models appearing in the MMP for $M_{\omega}(v)$.

Theorem (Bertram, M.)

Let X be an arbitrary smooth surface. Given two ample classes ω and ω' and a Chern character v there is a sequence of GIT flips



*where M_i and N_i are projective moduli spaces of Bridgeland semistable **sheaves** of type v .*

In general, how does the central charge Z_σ of a stability condition look like?

In general, how does the central charge Z_σ of a stability condition look like?

- (Bridgeland; Arcara, Bertram) If X is a surface and σ is geometric with $Z_\sigma(\mathbb{C}_X) = -1$ then there are classes $B, \omega \in N^1(X)_\mathbb{Q}$ with ω ample such that

$$Z_\sigma(E) = - \int e^{-B-i\omega} ch(E).$$

The Bridgeland “tilted” slope

The Bridgeland “tilted” slope

Let $ch^B := e^{-B} ch$,

The Bridgeland “tilted” slope

Let $ch^B := e^{-B} ch$, then

$$\mu_\sigma = \frac{\left(ch_2^B - \frac{\omega^2}{2} ch_0^B \right) \cdot \omega^{n-2}}{ch_1^B \cdot \omega^{n-1}}.$$

The Bridgeland “tilted” slope

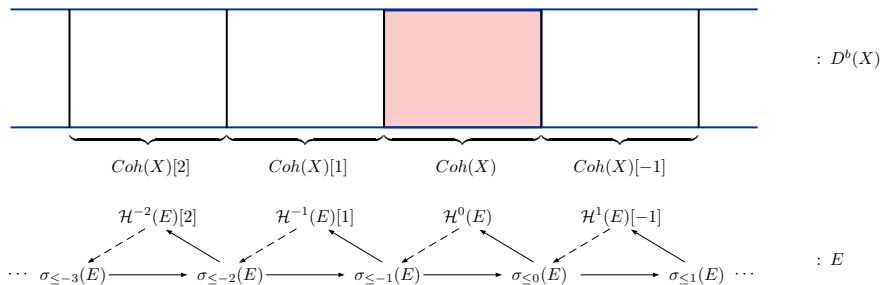
Let $ch^B := e^{-B} ch$, then

$$\mu_\sigma = \frac{\left(ch_2^B - \frac{\omega^2}{2} ch_0^B \right) \cdot \omega^{n-2}}{ch_1^B \cdot \omega^{n-1}}.$$

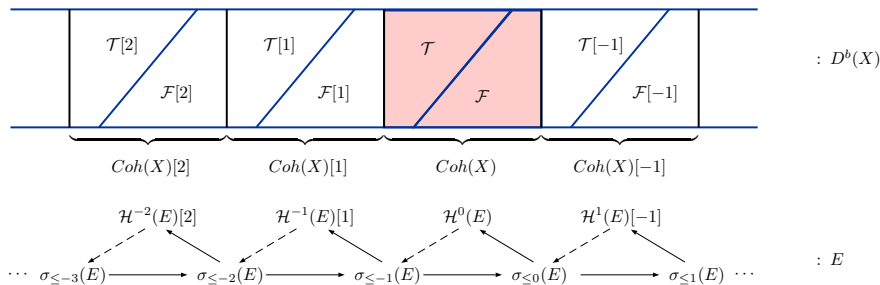
From now on we denote this tilted slope by $\nu_{B,\omega}$ and refer to it as **the tilt**.

How do we get new abelian categories from $Coh(X)$?

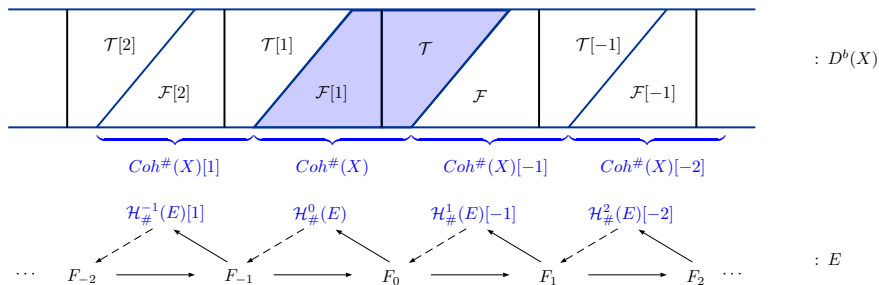
How do we get new abelian categories from $\text{Coh}(X)$?



How do we get new abelian categories from $\text{Coh}(X)$?



How do we get new abelian categories from $Coh(X)$?



How about the category \mathcal{A}_σ ?

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves,

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves, (\mathcal{T})

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves, (\mathcal{T})
 - μ_ω -semistable sheaves with $\mu_\omega > B\omega$,

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves, (\mathcal{T})
 - μ_ω -semistable sheaves with $\mu_\omega > B\omega$, (\mathcal{T})

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves, (\mathcal{T})
 - μ_ω -semistable sheaves with $\mu_\omega > B\omega$, (\mathcal{T})
 - $[1]$ shifts of μ_ω -semistable sheaves with $\mu_\omega \leq B\omega$

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves, (\mathcal{T})
 - μ_ω -semistable sheaves with $\mu_\omega > B\omega$, (\mathcal{T})
 - $[1]$ shifts of μ_ω -semistable sheaves with $\mu_\omega \leq B\omega$, $(\mathcal{F}[1])$

How about the category \mathcal{A}_σ ?

- \mathcal{A}_σ is obtained using the tilting process. Its objects are quasi-isomorphic to two-term complexes.
- \mathcal{A}_σ is generated by
 - torsion sheaves, (\mathcal{T})
 - μ_ω -semistable sheaves with $\mu_\omega > B\omega$, (\mathcal{T})
 - $[1]$ shifts of μ_ω -semistable sheaves with $\mu_\omega \leq B\omega$, $(\mathcal{F}[1])$
- Since \mathcal{A}_σ is obtained as a tilt of $\text{Coh}(X)$, from now on we will denote it by $\text{Coh}^{B,\omega}(X)$.

Douglas' central charge for Π -stability

$$Z_\sigma(E) = - \int e^{-B-i\omega} \sqrt{\text{td}(X)} \text{ch}(E) + \text{corrections.}$$

Douglas' central charge for Π -stability

$$Z_\sigma(E) = - \int e^{-B-i\omega} \sqrt{\text{td}(X)} \text{ch}(E) + \text{corrections.}$$

- On surfaces there is no need for corrections.

Douglas' central charge for Π -stability

$$Z_{\sigma}(E) = - \int e^{-B-i\omega} \sqrt{\text{td}(X)} ch(E) + \text{corrections.}$$

- On surfaces there is no need for corrections.
- The positivity property is a consequence of the Hodge Index Theorem and the Bogomolov inequality for slope semistable sheaves

Douglas' central charge for Π -stability

$$Z_{\sigma}(E) = - \int e^{-B-i\omega} \sqrt{\text{td}(X)} ch(E) + \text{corrections}.$$

- On surfaces there is no need for corrections.
- The positivity property is a consequence of the Hodge Index Theorem and the Bogomolov inequality for slope semistable sheaves

$$\Delta(E) \geq 0.$$

How about threefolds?

How about threefolds?

Conjecture (Bayer, Bertram, Macrì, Toda; 2011)

On a threefold X the linear map

$$Z_{B,\omega}(E) = - \int e^{-B-i\omega} ch(E)$$

defines a stability condition on the tilt $\mathcal{A}_{B,\omega}$ of $Coh^{B,\omega}(X)$ with respect to the tilted slope

$$\nu_{B,\omega} = \frac{(ch_2^B - \frac{\omega^2}{2} ch_0^B) \cdot \omega}{ch_1^B \cdot \omega^2}.$$

How about threefolds?

Conjecture (Bayer, Bertram, Macrì, Toda; 2011)

On a threefold X the linear map

$$Z_{B,\omega}(E) = - \int e^{-B-i\omega} ch(E)$$

defines a stability condition on the tilt $\mathcal{A}_{B,\omega}$ of $Coh^{B,\omega}(X)$ with respect to the tilted slope

$$\nu_{B,\omega} = \frac{(ch_2^B - \frac{\omega^2}{2} ch_0^B) \cdot \omega}{ch_1^B \cdot \omega^2}.$$

*No corrections required!

Equivalently

Theorem (Bayer, Macrì, Toda)

The pair $(Z_{B,\omega}, \mathcal{A}_{B,\omega})$ defines a geometric stability condition on X if and only if every $\nu_{B,\omega}$ -semistable object $E \in \text{Coh}^{B,\omega}(X)$ with $\nu_{B,\omega}(E) = 0$ also satisfies

$$ch_3^B(E) - \frac{\omega^2}{6} ch_1^B(E) \leq 0.$$

Generalized Bogomolov-Gieseker inequality

Theorem (Bayer, Macrì, Toda)

The pair $(Z_{B,\omega}, \mathcal{A}_{B,\omega})$ defines a geometric stability condition on X if and only if every $\nu_{B,\omega}$ -semistable object $E \in \text{Coh}^{B,\omega}(X)$ with $\nu_{B,\omega}(E) = 0$ also satisfies

$$ch_3^B(E) - \frac{\omega^2}{6} ch_1^B(E) \leq 0.$$

Known cases:

Known cases:

- \mathbb{P}^3 .

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$.

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds.

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)
- Fano threefolds of Picard number 1.

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)
- Fano threefolds of Picard number 1. (Li)

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)
- Fano threefolds of Picard number 1. (Li)
- Some product threefolds.

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)
- Fano threefolds of Picard number 1. (Li)
- Some product threefolds. (Koseki)

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)
- Fano threefolds of Picard number 1. (Li)
- Some product threefolds. (Koseki)
- The quintic threefold.

Known cases:

- \mathbb{P}^3 . (Bayer, Macrì, Toda; Macrì)
- Quadric $Q \subset \mathbb{P}^4$. (Schmidt)
- Abelian threefolds. (Piyaratne, Maciocia; Bayer, Macrì, Stellari)
- Fano threefolds of Picard number 1. (Li)
- Some product threefolds. (Koseki)
- The quintic threefold. (Li)

Oops

Oops

- Conjecture fails on $Bl_p\mathbb{P}^3$.

Oops

- Conjecture fails on $Bl_p\mathbb{P}^3$. Schmidt proves the existence of classes β, ω and a line bundle so that the GBG inequality fails.

Oops

- Conjecture fails on $B\mathbb{P}^3$. Schmidt proves the existence of classes β, ω and a line bundle so that the GBG inequality fails.
- Does this mean that there should be corrections to the central charge?

How do we construct new counterexamples?

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves.

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves. Indeed, suppose that $C \subset X$ is a curve of negative self intersection.

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves. Indeed, suppose that $C \subset X$ is a curve of negative self intersection. Then

$$\Delta(\mathcal{O}_C)$$

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves. Indeed, suppose that $C \subset X$ is a curve of negative self intersection. Then

$$\Delta(\mathcal{O}_C) = ch_1(\mathcal{O}_C)^2 - 2ch_0(\mathcal{O}_C)ch_2(\mathcal{O}_C)$$

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves. Indeed, suppose that $C \subset X$ is a curve of negative self intersection. Then

$$\Delta(\mathcal{O}_C) = ch_1(\mathcal{O}_C)^2 - 2ch_0(\mathcal{O}_C)ch_2(\mathcal{O}_C) = C^2$$

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves. Indeed, suppose that $C \subset X$ is a curve of negative self intersection. Then

$$\Delta(\mathcal{O}_C) = ch_1(\mathcal{O}_C)^2 - 2ch_0(\mathcal{O}_C)ch_2(\mathcal{O}_C) = C^2 < 0.$$

How do we construct new counterexamples?

- Classical Bogomolov inequality on a surface also fails for some Gieseker semistable sheaves. Indeed, suppose that $C \subset X$ is a curve of negative self intersection. Then

$$\Delta(\mathcal{O}_C) = ch_1(\mathcal{O}_C)^2 - 2ch_0(\mathcal{O}_C)ch_2(\mathcal{O}_C) = C^2 < 0.$$

- Can we find divisors D on a threefold X with special intersection properties so that \mathcal{O}_D violates the GBG inequality?

Using Bertram's estimates for walls...

Theorem (M., Schmidt)

Let X be a smooth projective threefold. Suppose that there is an effective divisor D and an ample divisor H such that

$$D^3 > \frac{(D \cdot H^2)^3}{4(H^3)^2} + \frac{3(D^2 \cdot H)^2}{4D \cdot H^2}.$$

Then there exists a pair of numbers $\alpha_0 > 0, \beta_0$ such that \mathcal{O}_D violates the GBG inequality for $\omega = \alpha_0 H$ and $B = \beta_0 H$.

Using Bertram's estimates for walls...

Theorem (M., Schmidt)

Let X be a smooth projective threefold. Suppose that there is an effective divisor D and an ample divisor H such that

$$D^3 > \frac{(D \cdot H^2)^3}{4(H^3)^2} + \frac{3(D^2 \cdot H)^2}{4D \cdot H^2}.$$

Then there exists a pair of numbers $\alpha_0 > 0, \beta_0$ such that \mathcal{O}_D violates the GBG inequality for $\omega = \alpha_0 H$ and $B = \beta_0 H$.

*We require $\rho(X) > 1$.

Counterexample 1

Suppose that there is a projective morphism $\pi: X \rightarrow X_0$ with exceptional locus a divisor D that gets contracted to a point by π . Then the GBG inequality fails on X with

Counterexample 1

Suppose that there is a projective morphism $\pi: X \rightarrow X_0$ with exceptional locus a divisor D that gets contracted to a point by π . Then the GBG inequality fails on X with

$$H = m\pi^*A - D, \text{ where } A \text{ is ample on } X_0 \text{ and } m \gg 0.$$

Counterexample 1

Suppose that there is a projective morphism $\pi: X \rightarrow X_0$ with exceptional locus a divisor D that gets contracted to a point by π . Then the GBG inequality fails on X with

$$H = m\pi^*A - D, \text{ where } A \text{ is ample on } X_0 \text{ and } m \gg 0.$$

In particular, the GBG inequality fails on any blow-up of a point on a smooth threefold.

Counterexample 2

Let $p: Y \rightarrow B$ be a smooth elliptic Calabi-Yau threefold over a del Pezzo surface B with a section $\sigma: B \rightarrow Y$. Then the GBG inequality fails on Y with:

Counterexample 2

Let $p: Y \rightarrow B$ be a smooth elliptic Calabi-Yau threefold over a del Pezzo surface B with a section $\sigma: B \rightarrow Y$. Then the GBG inequality fails on Y with:

- $D = \Theta \subset Y$ the image of σ .

Counterexample 2

Let $p: Y \rightarrow B$ be a smooth elliptic Calabi-Yau threefold over a del Pezzo surface B with a section $\sigma: B \rightarrow Y$. Then the GBG inequality fails on Y with:

- $D = \Theta \subset Y$ the image of σ .
- $H = t\Theta - (1+t)p^*K_B$ and $t > 2^{1/3} - 1$.

Counterexample 2

Let $p: Y \rightarrow B$ be a smooth elliptic Calabi-Yau threefold over a del Pezzo surface B with a section $\sigma: B \rightarrow Y$. Then the GBG inequality fails on Y with:

- $D = \Theta \subset Y$ the image of σ .
- $H = t\Theta - (1 + t)p^*K_B$ and $t > 2^{1/3} - 1$.

Counterexample 2

Let $p: Y \rightarrow B$ be a smooth elliptic Calabi-Yau threefold over a del Pezzo surface B with a section $\sigma: B \rightarrow Y$. Then the GBG inequality fails on Y with:

- $D = \Theta \subset Y$ the image of σ .
- $H = t\Theta - (1+t)p^*K_B$ and $t > 2^{1/3} - 1$.

Note: ALL known counterexamples to the GBG inequality are constructed this way.

Can we understand the corrections to the central charge in the case of blow ups?

Can we understand the corrections to the central charge in the case of blow ups?

- Let $f : \tilde{X} \rightarrow X$ be the blow-up of X at P and denote by E the exceptional divisor.

Can we understand the corrections to the central charge in the case of blow ups?

- Let $f : \tilde{X} \rightarrow X$ be the blow-up of X at P and denote by E the exceptional divisor.
- Let H be ample on X and assume that $(Z_{\alpha H, B_0 + \beta H}, \mathcal{A}_{\alpha H, B_0 + \beta H})$ is a stability condition on X .

Can we understand the corrections to the central charge in the case of blow ups?

- Let $f : \tilde{X} \rightarrow X$ be the blow-up of X at P and denote by E the exceptional divisor.
- Let H be ample on X and assume that $(Z_{\alpha H, B_0 + \beta H}, \mathcal{A}_{\alpha H, B_0 + \beta H})$ is a stability condition on X .
- Can we use $(Z_{\alpha H, B_0 + \beta H}, \mathcal{A}_{\alpha H, B_0 + \beta H})$ to construct a stability condition on \tilde{X} ?

Can we understand the corrections to the central charge in the case of blow ups?

- Let $f : \tilde{X} \rightarrow X$ be the blow-up of X at P and denote by E the exceptional divisor.
- Let H be ample on X and assume that $(Z_{\alpha H, B_0 + \beta H}, \mathcal{A}_{\alpha H, B_0 + \beta H})$ is a stability condition on X .
- Can we use $(Z_{\alpha H, B_0 + \beta H}, \mathcal{A}_{\alpha H, B_0 + \beta H})$ to construct a stability condition on \tilde{X} ?

Let's define some classes

Let's define some classes

- $\tilde{H} = f^* H,$

Let's define some classes

- $\tilde{H} = f^* H,$
- $\tilde{B}_0 = f^* B_0 - 2E,$

Let's define some classes

- $\tilde{H} = f^* H,$
- $\tilde{B}_0 = f^* B_0 - 2E,$
- $\tilde{B} = \tilde{B}_0 + \beta \tilde{H},$

Let's define some classes

- $\tilde{H} = f^* H,$
- $\tilde{B}_0 = f^* B_0 - 2E,$
- $\tilde{B} = \tilde{B}_0 + \beta \tilde{H},$

Theorem (M., Schmidt)

There is a heart of a t -structure $\tilde{\mathcal{A}}$ on $D^b(\tilde{X})$ such that the linear map

$$Z_{\alpha,\beta,s} = - \left(ch_3^{\tilde{B}} - s\alpha^2 \tilde{H}^2 ch_1^{\tilde{B}} - \frac{E^2}{6} ch_1^{\tilde{B}} \right) + i \left(\tilde{H} ch_2^{\tilde{B}} - \frac{\alpha^3}{2} \tilde{H}^3 ch_0^{\tilde{B}} \right)$$

is the central charge of a stability condition on $\tilde{\mathcal{A}}$ for every $s > 1/6$ if and only if

$$Z_{\alpha H, B_0 + \beta H} = - \left(ch_3^B - s\alpha^2 H^2 ch_1^B \right) + i \left(H ch_2^B - \frac{\alpha^3}{2} H^3 ch_0^B \right)$$

is the charge of a stability condition on $\mathcal{A}_{\alpha H, B_0 + \beta H}$, i.e., if and only if the GBG inequality holds on X for the classes $B_0 + \beta H$ and αH .

Some open questions and projects

Some open questions and projects

- Can we run an MMP for moduli spaces of sheaves on other surfaces using variation of stability conditions? For instance, on a Hirzebruch surface?

Some open questions and projects

- Can we run an MMP for moduli spaces of sheaves on other surfaces using variation of stability conditions? For instance, on a Hirzebruch surface?
 - With Talon Stark (UCLA). To relate the birational models of the Gieseker moduli appearing in an MMP to moduli spaces of Bridgeland semistable objects, for a fixed Chern character we would like to find families of stability conditions with projective moduli. We work with exceptional collections on Hirzebruch surfaces to produce such families.

Some open questions and projects

- Can we run an MMP for moduli spaces of sheaves on other surfaces using variation of stability conditions? For instance, on a Hirzebruch surface?
 - With Talon Stark (UCLA). To relate the birational models of the Gieseker moduli appearing in an MMP to moduli spaces of Bridgeland semistable objects, for a fixed Chern character we would like to find families of stability conditions with projective moduli. We work with exceptional collections on Hirzebruch surfaces to produce such families.

Some open questions and projects

Some open questions and projects

- Can we study the Bridgeland wall-crossing for moduli spaces of sheaves on \mathbb{P}^3 ? In particular, can we prove projectivity? Can we describe the birational transformations geometrically?

Some open questions and projects

- Can we study the Bridgeland wall-crossing for moduli spaces of sheaves on \mathbb{P}^3 ? In particular, can we prove projectivity? Can we describe the birational transformations geometrically?
 - With Benjamin Schmidt (Leibniz Universität Hannover). If we fix the Chern character of a 1-dimensional space sheaf or an instanton sheaf then there is a 2-dimensional family of stability conditions with a finite wall and chamber decomposition that recovers the Gieseker moduli in the outermost chamber. Can we develop algorithms to effectively compute all the wall-crossings?

Some open questions and projects

- Can we study the Bridgeland wall-crossing for moduli spaces of sheaves on \mathbb{P}^3 ? In particular, can we prove projectivity? Can we describe the birational transformations geometrically?
 - With Benjamin Schmidt (Leibniz Universität Hannover). If we fix the Chern character of a 1-dimensional space sheaf or an instanton sheaf then there is a 2-dimensional family of stability conditions with a finite wall and chamber decomposition that recovers the Gieseker moduli in the outermost chamber. Can we develop algorithms to effectively compute all the wall-crossings?

Some open questions and projects

Some open questions and projects

- We have proven that it is possible to construct stability conditions on a blow up of a smooth threefold at a point by pulling back stability conditions on the threefold. However, the induced stability conditions depend on a nef class rather than on an ample class. For what type of nef classes would it be possible to construct tilts of $Coh(X)$?

Some open questions and projects

- We have proven that it is possible to construct stability conditions on a blow up of a smooth threefold at a point by pulling back stability conditions on the threefold. However, the induced stability conditions depend on a nef class rather than on an ample class. For what type of nef classes would it be possible to construct tilts of $Coh(X)$?
 - With Jason Lo (California State University, Northridge). Can we produce a correction term for the GBG inequality on an elliptic Calabi-Yau threefold with a section over a del Pezzo surface?

Some open questions and projects

- We have proven that it is possible to construct stability conditions on a blow up of a smooth threefold at a point by pulling back stability conditions on the threefold. However, the induced stability conditions depend on a nef class rather than on an ample class. For what type of nef classes would it be possible to construct tilts of $Coh(X)$?
 - With Jason Lo (California State University, Northridge). Can we produce a correction term for the GBG inequality on an elliptic Calabi-Yau threefold with a section over a del Pezzo surface?

Some open questions

Some open questions

- On elliptic fibrations we have an extra tool, the relative Fourier-Mukai transform. In joint work with Wanmin Liu and Jason Lo we proved that for the case of elliptic surfaces with a section, the relative FM transform preserves Bridgeland stability for stability conditions on certain paths in $Stab(X)$. Moreover, the FM transform sends $Coh(X)$ to a tilt of $Coh(X)$. Can we do the same for elliptic Calabi-Yau threefolds with a section?

Some open questions

- On elliptic fibrations we have an extra tool, the relative Fourier-Mukai transform. In joint work with Wanmin Liu and Jason Lo we proved that for the case of elliptic surfaces with a section, the relative FM transform preserves Bridgeland stability for stability conditions on certain paths in $Stab(X)$. Moreover, the FM transform sends $Coh(X)$ to a tilt of $Coh(X)$. Can we do the same for elliptic Calabi-Yau threefolds with a section?
- If we know that the relative FM transform send a tilt of $Coh(X)$ to a double tilt of $Coh(X)$, then we can study the image of the Bogomolov form by the FM transform.

Some open questions

- On elliptic fibrations we have an extra tool, the relative Fourier-Mukai transform. In joint work with Wanmin Liu and Jason Lo we proved that for the case of elliptic surfaces with a section, the relative FM transform preserves Bridgeland stability for stability conditions on certain paths in $Stab(X)$. Moreover, the FM transform sends $Coh(X)$ to a tilt of $Coh(X)$. Can we do the same for elliptic Calabi-Yau threefolds with a section?
- If we know that the relative FM transform send a tilt of $Coh(X)$ to a double tilt of $Coh(X)$, then we can study the image of the Bogomolov form by the FM transform. In the case that X is elliptically fibered over a del Pezzo surface and $\omega = \Theta - 2p^*(K_B)$ then the image of the discriminant by the FM transform is

$$\left(3ch_0(\Phi E)K_B^2 - ch_2(\Phi E) \cdot p^*K_B\right)^2 + 7K_B^2 ch_1(\Phi E) \cdot f \left(\left(1 + \frac{1}{24}\right) K_B^2 ch_1(\Phi E) \cdot f - ch_1(\Phi E) \cdot \Theta^2 - ch_3(\Phi E) \right) \geq 0.$$

Thank you!